

METHOD II. Suppose  $d_i = p_i C$  and  $p_i \geq 0$  for  $i = 1, 2, \dots, m$ . This case can have a binary coded table consisting of two rows. The first row,  $s$ , is used to keep a record of which sequence value has been generated by using the second row. Let  $t_i = p_i$  if  $p_i \neq 0$ ; otherwise let  $t_i = 1$ . Let  $B_{sj} = 1$  for  $j = t_1, t_1 + t_2, \dots, t_1 + t_2 + \dots + t_m$ . Let  $B_{sj} = 1$  for  $j = 1 + \sum_{i=1}^{k-1} t_i, \dots, p_k + \sum_{i=1}^{k-1} t_i$  where  $k = 1, 2, \dots, m$ . The  $s$  row contains  $m$  bits while the second row contains  $\sum_{i=1}^m p_i$  bits. This method requires  $2 \sum_{i=1}^m t_i$  bit positions of memory. For an example of this method, Sequence  $B$  can have the binary coded table given in Table I by using Rows 8 and 9, where 8 is the  $s$  row. In this case the coding to find  $x_n$ , given  $n$ , is done so that the  $x_0$  accumulator is incremented by  $C$  according to the second row, to the  $n$ th bit in the  $s$  row. If  $p_i \neq 0$  for  $i = 1, 2, \dots, m$  the second row would not have a blank position and therefore by suitable programming would not be necessary.

Suppose  $d_i = D + p_i C$  and  $p_i \geq 0$  for  $i = 1, 2, \dots, m$ . This sequence could have the same binary coded table as  $d_i = p_i C$  and  $p_i \geq 0$  for  $i = 1, 2, \dots, m$  if in the program  $D$  was added to the  $x_0$  accumulator for each  $B_{sj} = 1$  where  $j \leq n$ .

It is possible to use one  $s$  row when binary coding  $q$  sequences using Method II. Let  $L_j = \max(t_{1j}, \dots, t_{qj})$  where  $t_{ij}$  is  $t_i$  of the  $j$ th sequence. Let  $B_{sj} = 1$  for  $j = L_1, L_1 + L_2, \dots, L_1 + L_2 + \dots + L_m$ . Let  $B_{Hn} = 1$  for  $n = 1 + \sum_{i=1}^{k-1} L_i, \dots, p_k + \sum_{i=1}^{k-1} L_i$  where  $k = 1, 2, \dots, m$  and for  $H = 1, 2, \dots, q$ . For example, Sequences  $B, C$  and  $D$  can be generated using in Table I Rows 11, 12, 13 and 14, where Row 11 is the  $s$ -row. This same procedure could be followed to binary code  $d_i = t_{1i}C_1 + t_{2i}C_2 + \dots + t_{qi}C_q$ , where  $t_{ji} \geq 0$  and  $i = 1, 2, \dots, m$ .

TABLE I

Sequences:

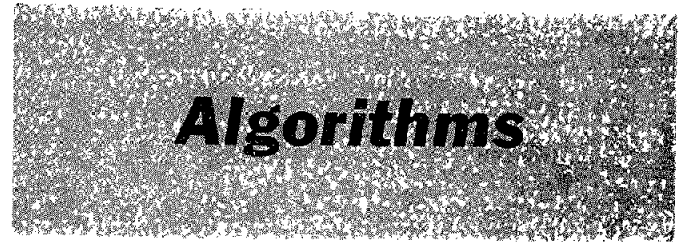
A	B	C	D
0	1	16	119
1	3	16	120
2	4	18	122
3	7	24	122
5	8	24	123
7	10	26	125
10	12	30	127
11	13	32	128
14	13	34	129
16	15	36	129
18			
21			
22			

1	x	x	x			x				x									
2				x	x			x	x										
3						x		x			x								
4																			
5	x	x	x			x	x	x			x	x							
6				x	x	x		x	x	x	x								
7																			
8		x	x			x	x		x		x	x	x			x			
9	x	x	x	x	x	x	x	x	x	x	x	x	x			x	x		
10																			
11		x		x		x	x		x		x	x	x			x			
12	x	x	x		x	x	x	x	x	x	x	x	x			x	x		
13			x		x	x	x		x		x	x	x	x		x			
14	x		x	x				x	x	x	x	x	x			x			

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ALGORITHM 223

PRIME TWINS

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```

procedure PrimeTwins (t, Twin1, Twin2, Storage, Act);
  value Storage; integer t, Twin1, Twin2, Storage;
  procedure Act;
  comment This procedure will generate successive "prime
  twins," i.e. pairs of primes Twin1, Twin2 which differ by 2.
  Storage is the maximum number of primes that can be stored.
  Act is any procedure for recording, examining, or utilizing each
  pair of twins as it is generated. t is a serial number for the
  twins. P[Storage] ↑ 2 is the last number examined;
  begin integer array P[1: Storage]; integer j, m, previous,
  current;
  comment P[j] is the jth prime;
  P[1] := 2; P[2] := 3; j := 2; previous := 3; t := 0;
  for current := 5 step 2 until P[j] × P[j] do
  begin m := 1; for m := m + 1 while P[m] × P[m] ≤ cur-
  rent do
  if current = (current ÷ P[m]) × P[m] then go to NoPrime;
  comment If this point is reached, current is not divisible by
  any prime up to sqrt(current) and so is a prime. We now
  record the new prime, if storage permits, then check if it
  is the second of twins;
  if j < Storage then
  begin j := j + 1; P[j] := current
  end;
  if current = previous + 2 then
  begin t := t + 1; Twin1 := previous; Twin2 := current;
  Act (t, Twin1, Twin2)
  end;
  previous := current;
  NoPrime:
  end;
end procedure PrimeTwins
  
```

ALGORITHM 224

EVALUATION OF DETERMINANT

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(Recd 7 Oct. 1963; in final form 20 Dec. 1963)  
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```

real procedure determinant (a, n);
  value n; real array a; integer n;
  comment This procedure evaluates a determinant by triangulari-
  zation. The matrix supplied by the calling procedure is modified
  by this program. This procedure is an extensive revision and
  correction of Algorithm 41;
  begin real product, factor, temp, div, piv, abpiv, maxpiv;
  integer ssign, i, j, r, imax;
  ssign := 1; product := 1.0;
  for r := 1 step 1 until n-1 do
  begin maxpiv := 0.0;
  for i := r step 1 until n do
  
```

```

begin piv := a[i, r];
abpiv := abs(piv);
if abpiv > maxpiv then
begin maxpiv := abpiv;
div := piv;
imax := i
end
end;
if maxpiv ≠ 0.0 then
begin if imax = i then go to resume else
begin for j := r step 1 until n do
begin temp := a[imax, j];
a[imax, j] := a[r, j];
a[r, j] := temp
end;
ssign := -ssign;
go to resume
end
end;
determinant := 0.0;
go to return;
resume: for i := r+1 step 1 until n do
begin factor := a[i, r]/div;
for j := r+1 step 1 until n do
a[i, j] := a[i, j] - factor × a[r, j]
end
end;
for i := 1 step 1 until n do
product := product × a[i, i];
comment Exponent overflow or underflow will most likely
occur here if at all. For large or small determinants the user
is cautioned to replace this with a call to a machine-language
product routine which will handle extremely large or small
real numbers;
determinant := ssign × product;
return;
end

```

CERTIFICATION OF ALGORITHM 182  
NONRECURSIVE ADAPTIVE INTEGRATION [W.  
M. McKeeman and Larry Tesler, *Comm. ACM* 6 (June  
1963), 315]

HAROLD S. BUTLER (Recd 8 Nov. 1963; rev. 6 Dec. 1963)  
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A BALGOL transliteration of *Simpson* has been prepared at Stanford by its authors and it has been used in a number of problems involving numerical integration. Its value was most strikingly displayed when it was utilized in a triple integral in which the final integration was over a strongly peaked function that spanned seven orders of magnitude. *Simpson* effectively minimized the number of evaluations and completed the integration five times faster than alternate schemes to subdivide the region of interest. The values of the integral agreed with independent calculations well within the required tolerance.

The following changes should be made to the published algorithm:

Line 13 should be changed to:

```
lv1 := 0; absarea := est := 1.0; da := b-a;
```

Line 17 should read:

```
sx := dx[lv1]/6.0; F1 := 4.0 × F(a + dx[lv1]/2.0);
```

Line 20 should read:

```
epsp[lv1] := eps; F4[lv1] := 4.0 × F(x3[lv1] + dx[lv1]/2.0);
```

The condition of line 27 should be changed to:

```
if ((abs(est-sum) ≤ epsp[lv1] × absarea) ∧ (est ≠ 1.0)) ∨
(lv1 ≥ 30) then
```

CERTIFICATION OF ALGORITHMS 191 AND 192  
HYPERGEOMETRIC AND CONFLUENT HYPER-  
GEOMETRIC [A. P. Relph, *Comm. ACM* 6 (July  
1963), 388]

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\* Work supported by the U.S. Atomic Energy Commission.

The bodies of these two procedures were transcribed for the Dartmouth SCALP processor for the LCP 30 computer. No syntactical errors were found, and the programs gave results agreeing within roundoff (7D) with tabulated values for the following special cases:  ${}_2F_1(0.5, 0.5; 1; k^2) = (2/\pi) K(k)$ ;  ${}_2F_1(0.5, -0.5; 1; k^2) = (2/\pi) E(k)$  where  $K$  and  $E$  are complete elliptic integrals of the first and second kinds;  ${}_1F_1(.5; 1; iy) = J_0(x)$ , and with  ${}_1F_1(-1; 0.1; x)$ ;  ${}_1F_1(-0.5; 0.1; x)$ , and  ${}_1F_1(-0.5; 0.5; x)$ .

It should be observed that the function calculated by 191 is  ${}_2F_1(a, b; c; z)$ , not  ${}_1F_2(a, b; c; z)$  as stated in the comment. These programs evaluate the functions by direct summation of the hypergeometric series. They are, therefore, relatively general, but inefficient. Precautions must also be taken against attempting to compute outside the range of effective convergence of the series.

CERTIFICATION OF ALGORITHM 222  
INCOMPLETE BETA FUNCTION RATIOS [Walter  
Gautschi, *Comm. ACM* 7 (March 1964), 143]

WALTER GAUTSCHI (Recd 2 Jan. 1964)

Purdue Univ., Lafayette, Ind.

```
begin integer n; array I1, I2, I3[0:10];
```

comment This program calls the procedures *Incomplete beta q fixed* and *Incomplete beta p fixed* to calculate test values of  $I_{.4}(.5+n, 7)$ ,  $I_{.4}(5, 1+n)$ ,  $I_{.8}(5, 1+n)$  for  $n = 0(1)10$  to 6 significant digits. The following results were obtained on the CDC 1604-A computer, using the Oak Ridge ALGOL compiler:

n	$I_{.4}(.5+n, 7)$	$I_{.4}(5, 1+n)$	$I_{.8}(5, 1+n)$
0	.99143646185	.010239999997	.32768000004
1	.93951533330	.040959999972	.65536000000
2	.83567307612	.096255999927	.85196799999
3	.69444760641	.17367039987	.94371839999
4	.54111709640	.26656767980	.98041856000
5	.39800862042	.36689674211	.99363061758
6	.27831789503	.46722580441	.99803463679
7	.18624810627	.56182177742	.99941875711
8	.11995785836	.64695815314	.99983399319
9	.074724512738	.72074301208	.99995395031
10	.045203802963	.78272229360	.99998753828

All results are in agreement with those tabulated in [1];

*Incomplete beta q fixed* (.4, .5, 7, 10, 6, I1);

*Incomplete beta p fixed* (.4, 5, 1, 10, 6, I2);

*Incomplete beta p fixed* (.8, 5, 1, 10, 6, I3);

```
for n := 0 step 1 until 10 do
```

```
write ( I1[n], I2[n], I3[n] )
```

```
end Driver incomplete beta function ratios
```

In the original publication of the algorithm, the following correction of a printer's error is needed in the real procedure *Isubx p and q small*. The statement labelled L0 should read as follows:

```
u := (k - q + 1) × x × u/(k + 1);
```

[1] PEARSON, K. *Tables of the Incomplete Beta-Function*. Cambridge University Press, London, 1934.