

ALGORITHM 313  
MULTI-DIMENSIONAL PARTITION  
GENERATOR [A1]

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**procedure** *partition* (*N*, *dim*, *use*);  
**value** *N*, *dim*; **integer** *N*, *dim*; **procedure** *use*;  
**comment** A partition of *N* is an ordered sequence of positive  
integers,  $n_1 \geq n_2 \geq n_3 \geq \dots \geq n_k$ , such that  $\sum_{i=1}^k n_i = N$ .

Such a partition may be represented by a Ferrers-Sylvester  
graph of nodes with  $n_i$  nodes in the *i*th row, e.g.,

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* * * *
* *
* *

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represents 5, 4, 2, 2. This two-dimensional diagram may be gen-  
eralized in a natural way to three, or more, dimensions. More  
formally, we regard a *d*-dimensional partition of *n* as a set *S* of  
*n* nodes, each defined by its non-negative integer coordinates  
such that

$(x_1, x_2, \dots, x_d) \in S$  if and only if  $(x_1', x_2', \dots, x_d') \in S$   
whenever

$$0 \leq x_i' \leq x_i \text{ for all } i = 1, 2, \dots, d.$$

This generalization reduces to the usual definition when *d* = 2.  
There is little literature on these generalized partitions. It is  
with a view to facilitating numerical studies that this algorithm  
is published.

After generation, each partition is presented to the procedure  
*use*, which should be supplied by the user for the purpose he  
requires. *use* has three formal parameters, the first being the  
name of a two-dimensional integer array, and the second and  
third being integers giving the size of this array. When the pro-  
cedure is called by

*use* (*current*, *dim*, *N*)

then the coordinates of the nodes entering into the newly  
generated multi-dimensional partition will be found in *current*  
[1:*dim*,1:*N*]. The parameters of *use* should be called by value,  
or alternatively care should be taken that neither *dim*, *N*, nor  
the contents of the array *current* are disturbed.

REFERENCES:

- GUPTA, H., GWYTHYR, C. E., AND MILLER, J. C. P. *Tables of Partitions*. Royal Society Mathematical Tables, Vol. 4, Cambridge Univ. Press, 1958.
- MACMAHON, P. A. *Combinatory Analysis*, Vol. 2, Cambridge Univ. Press, 1916.
- CHAUNDY, T. W. Partition generating functions. *Quart. J. Math.* 2 (1931), 234-240.
- ATKIN, A. O. L., BRATLEY, P., MACDONALD, I. G., AND MCKAY, J. K. S. Some computations for *m*-dimensional partitions. *Proc. Cambridge Phil. Soc.* (to appear);

**begin**

**integer** *i*; **integer array** *current* [1:*dim*, 1:*N*],  
*x*[1:*dim*,0:(*N*-1)×*dim*];  
**procedure** *part* (*n*,*q*,*r*); **value** *n*, *q*, *r*; **integer** *n*, *q*, *r*;  
**begin integer** *s*, *i*, *j*, *k*, *p*, *m*, *z*;  
**for** *p* := *q* **step** 1 **until** *r* - 1 **do**  
**begin**  
**for** *i* := 1 **step** 1 **until** *dim* **do** *current* [*i*,*n*] := *x*[*i*,*p*];  
**if** *n* = *N* **then begin use** (*current*,*dim*,*N*); **go to** L2 **end**;  
*s* := *r*;  
**for** *i* := 1 **step** 1 **until** *dim* **do**  
**begin**  
**for** *j* := 1 **step** 1 **until** *dim* **do** *x*[*j*,*s*] := *x*[*j*,*p*];

*x*[*i*,*s*] := *x*[*i*,*s*] + 1;  
**for** *j* := 1 **step** 1 **until** *dim* **do**  
**begin**  
**if** *x*[*j*, *s*] = 0 **then go to** L3;  
**for** *k* := 1 **step** 1 **until** *n* **do**  
**begin**  
**for** *m* := 1 **step** 1 **until** *dim* **do**  
**begin**  
*z* := **if** *j* = *m* **then** 1 **else** 0;  
**if** *current* [*m*, *k*] ≠ *x*[*m*,*s*] - *z* **then go to** L4  
**end**;  
**go to** L3;

L4:

**end** *k*;  
**go to** L5;

L3:

**end** *j*;  
*s* := *s* + 1;

L5:

**end** *i*;  
*part* (*n*+1,*p*+1,*s*);

L2: **end** *p*

**end** *part*;  
**for** *i* := 1 **step** 1 **until** *dim* **do** *x*[*i*,0] := 0; *part* (1,0,1)  
**end** *partition*

REMARK ON CORRECTION TO CERTIFICATION  
OF ALGORITHM 279 [D1]

CHEBYSHEV QUADRATURE [F.R.A. HOPGOOD AND  
C. LITHERLAND, *Comm. ACM* 9 (Apr. 1966), 270 and 10  
(May 1967), 294]

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There are two corrections that should be appended to the certi-  
fication of Algorithm 279.

Due to programming error, the integrand function routines for  
 $e^{-x^2}$  and  $\sin(x)+1$ , used by the Chebyshev routine, incorrectly  
evaluated the functions at  $x = 0$ , thus delaying convergence.

The revised Chebyshev routine still converges more rapidly  
than the original scheme in the first two examples, but the advan-  
tage is much less pronounced than previously indicated.

The amended Table I should read as follows, with the numerical  
corrections italicized.

TABLE I

Integrand	A	B	EPS	VI	Routine	VA	Number of function evaluations
$e^{-x^2}$	0	4.3	$10^{-6}$	0.886226924	Havie	0.886226924	17
					Romberg	0.886226925	65
					Chebyshev	<i>0.8862269261</i>	33
					Chebyshev (Rev.)	0.8862269258	17
$\sin(x)+1$	0	$2\pi$	$10^{-6}$	6.283185308	Havie	<i>6.283185307</i>	3
					Romberg	<i>6.283185307</i>	3
					Chebyshev	<i>6.2831853086</i>	9
					Chebyshev (Rev.)	6.2831853089	5