



Write a C program to determine whether a X by Y rectangle can fit within a square of side S , and if so, print the minimum angle it has to be rotated by in order to fit.

A rectangle of width X and height Y fits in a square of side S at some rotation θ iff there exists $\theta \in [0, \pi/2]$ such that

$$X \cos \theta + Y \sin \theta \leq S \quad \text{and} \quad X \sin \theta + Y \cos \theta \leq S, \quad \square \square$$

and the minimum such θ can be found by a 1D search.^{[1] [2]}

Below is a simple C program using doubles and a numeric search (binary search on θ) that:

- Reads X, Y, S .
- Checks if it can fit at all.
- If it can, finds the minimum angle in degrees to $1e-6$ precision.

```
#include <stdio.h>
#include <math.h>

static int can_fit(double w, double h, double s, double theta)
{
    double c = cos(theta);
    double t = sin(theta);

    /* Bounding box of rotated rectangle about its center:
       width' = w * fabs(c) + h * fabs(t)
       height' = w * fabs(t) + h * fabs(c) [web:9] */
    double bw = w * fabs(c) + h * fabs(t);
    double bh = w * fabs(t) + h * fabs(c);

    return (bw <= s + 1e-12 && bh <= s + 1e-12);
}

int main(void)
{
    double X, Y, S;

    if (scanf("%lf %lf %lf", &X, &Y, &S) != 3) {
        fprintf(stderr, "Usage: X Y S\n");
        return 1;
    }
}
```

```

/* Normalize so X >= Y, square is symmetric. */
if (Y > X) {
    double tmp = X;
    X = Y;
    Y = tmp;
}

/* Trivial checks. */
if (X <= S && Y <= S) {
    printf("Fits without rotation (angle = 0 degrees)\n");
    return 0;
}

/* If even at 45 degrees (pi/4) it doesn't fit, then no angle works. */
if (!can_fit(X, Y, S, M_PI / 4.0)) {
    printf("Does not fit in the square for any rotation.\n");
    return 0;
}

/* Binary search smallest angle in [0, pi/4] that fits. [web:11][web:13] */
double lo = 0.0;
double hi = M_PI / 4.0;
for (int i = 0; i < 80; ++i) { /* enough for ~1e-12 rad precision */
    double mid = 0.5 * (lo + hi);
    if (can_fit(X, Y, S, mid))
        hi = mid;
    else
        lo = mid;
}

double theta = hi; /* radians */
double degrees = theta * 180.0 / M_PI; /* to degrees */

printf("Fits. Minimum rotation angle: %.6f degrees\n", degrees);
return 0;
}

```

How it works

- The function `can_fit` computes the axis-aligned bounding box of the rectangle after rotation by θ about its center, which has side lengths $w \cos \theta + h \sin \theta$ and $w \sin \theta + h \cos \theta$ up to absolute values.^[1]
- The rectangle fits in the square iff both of those are $\leq S$.^[2]
- Because the configuration is symmetric, the minimum angle lies in $[0, \pi/4]$ if any angle works, so a binary search on that interval finds the smallest θ that satisfies the constraints.^{[3] [4]}

Can't it be solved using pythagoras' theorem without the iterative search?

For general X, Y, S there is no single Pythagoras-only closed-form for the *minimum* angle; you end up solving trig equations whose solution is transcendental, so numeric methods are standard. [\[19\]](#) [\[20\]](#)

What Pythagoras gives

- Pythagoras gives relations like $d^2 = X^2 + Y^2$ for the rectangle diagonal and $S^2 = S^2 + 0^2$ for the square side, and lets you compare the diagonal d with S . [\[21\]](#) [\[22\]](#)
- That is enough to answer "does it fit if aligned with a diagonal?" but not "what is the smallest rotation where the bounding box just equals $S \times S$?" [\[23\]](#) [\[19\]](#)

Why the angle needs trig

- The bounding box of a rotated X by Y rectangle is
 - width: $X \cos \theta + Y \sin \theta$
 - height: $X \sin \theta + Y \cos \theta$. [\[24\]](#) [\[19\]](#)
- The "just fits" condition is solving $X \cos \theta + Y \sin \theta = S$ and $X \sin \theta + Y \cos \theta = S$ together, which reduces to nonlinear equations in $\sin \theta$ and $\cos \theta$, not a single right triangle where Pythagoras alone applies. [\[25\]](#) [\[20\]](#)

When closed forms appear

- In special symmetric cases (e.g., $X = Y$ or specific aspect ratios) the minimum angle may be $0, 45^\circ$, or given by a simple arctan expression derived once you already used trig identities. [\[20\]](#) [\[19\]](#)
- For arbitrary X, Y, S , practical treatments use numeric search (binary search, Newton, etc.) over $\theta \in [0, \pi/4]$, which is robust and cheap in code. [\[19\]](#) [\[20\]](#)

✱

Then modify the requirement such that a 45 degree angle is used when it does not fit axis-aligned, then move the object to minimise X and Y for the bounding box of the rotated rectangle.

Yes; with your new requirement the geometry becomes simple, and you only need the 45° case plus a translation of the rotated rectangle so that its axis-aligned bounding box is minimized and centered.

Geometry at 45 degrees

For a rectangle X by Y , rotated by 45° about its center, the axis-aligned bounding box sides are

$$W = (X + Y)\frac{\sqrt{2}}{2}, \quad H = (X + Y)\frac{\sqrt{2}}{2}. \quad \square \square$$

So the bounding box is a square, and the rotated rectangle fits inside the square of side S if and only if

$$(X + Y)\frac{\sqrt{2}}{2} \leq S. \quad \square$$

Placement to minimize X and Y

- If you rotate about the rectangle center and then translate so that the bounding box is centered in the square, the bounding box extents are $\pm W/2$ and $\pm H/2$; this is the minimal possible axis-aligned bounding box for that orientation. [\[39\]](#) [\[40\]](#)
- There is no further translation that can reduce those W, H values; translating just shifts min/max but does not change width/height. [\[41\]](#) [\[39\]](#)

C code sketch

```
#include <stdio.h>
#include <math.h>

int main(void)
{
    double X, Y, S;
    const double SQRT2_OVER_2 = M_SQRT1_2; /* sqrt(2)/2 */

    if (scanf("%lf %lf %lf", &X, &Y, &S) != 3) {
        fprintf(stderr, "Usage: X Y S\n");
        return 1;
    }

    /* Axis-aligned fit first. */
    if (X <= S && Y <= S) {
        printf("Fits axis-aligned (angle = 0 degrees).\n");
        return 0;
    }

    /* 45-degree rotated bounding box size. */
    double W = (X + Y) * SQRT2_OVER_2; /* width == height at 45deg */

    if (W <= S) {
        /* Fits at 45 degrees; place centered in the square. */
        double angle_deg = 45.0;
        double bx = (S - W) * 0.5; /* bounding box min x */
        double by = (S - W) * 0.5; /* bounding box min y */
        printf("Fits at 45 degrees.\n");
        printf("Bounding box size: %.6f x %.6f\n", W, W);
        printf("Place bounding box with min corner at (%.6f, %.6f)\n",
```

```

        bx, by);
    printf("Rotation angle: %.6f degrees\n", angle_deg);
} else {
    printf("Does not fit even at 45 degrees.\n");
}

return 0;
}

```

- This uses the closed-form 45° bounding box formula; no iteration is needed. [\[40\]](#)
- The “minimize X and Y” is achieved by using the smallest possible axis-aligned bounding box at that angle (about the center) and then centering it in the square. [\[39\]](#) [\[40\]](#)

**

modify that solution to write a command-line program with parameters using gnu getopt parameter parsing for --x --y and --s 'long style' parameters (even though they are single-letter options in practice)

Below is a self-contained command-line program that uses `getopt_long` to parse `--x`, `--y`, and `--s` (also accepting `-x`, `-y`, `-s`) and then applies the “0° or 45° with centered bounding box” logic.

Program behavior

```
- Usage: `rectfit --x <width> --y <height> --s <square_side>`
```

- If X,Y fit axis-aligned within S, prints angle 0.
- Else checks 45° bounding box and, if it fits, prints angle 45°, bounding box size, and placement.
- Otherwise reports that it does not fit.

C source using `getopt_long`

```

#define _GNU_SOURCE
#include <stdio.h>
#include <stdlib.h>
#include <getopt.h>
#include <math.h>

static void usage(const char *prog)
{
    fprintf(stderr,
        "Usage: %s --x <width> --y <height> --s <square_side>\n"
        "        %s -x <width> -y <height> -s <square_side>\n",
        prog, prog);
}

```

```

}

/* Returns 0 on success, nonzero on error. */
int main(int argc, char *argv[])
{
    double X = 0.0, Y = 0.0, S = 0.0;
    int have_x = 0, have_y = 0, have_s = 0;

    static struct option long_opts[] = {
        { "x", required_argument, 0, 'x' },
        { "y", required_argument, 0, 'y' },
        { "s", required_argument, 0, 's' },
        { "help", no_argument, 0, 'h' },
        { 0, 0, 0, 0 }
    };

    int opt;
    int opt_index = 0;

    while ((opt = getopt_long(argc, argv, "x:y:s:h", long_opts, &opt_index)) != -1) {
        switch (opt) {
            case 'x':
                X = atof(optarg);
                have_x = 1;
                break;
            case 'y':
                Y = atof(optarg);
                have_y = 1;
                break;
            case 's':
                S = atof(optarg);
                have_s = 1;
                break;
            case 'h':
                usage(argv[4_0]);
                return 0;
            default:
                usage(argv[4_0]);
                return 1;
        }
    }

    if (!have_x || !have_y || !have_s) {
        usage(argv[4_0]);
        return 1;
    }

    if (X <= 0.0 || Y <= 0.0 || S <= 0.0) {
        fprintf(stderr, "All dimensions must be positive.\n");
        return 1;
    }

    /* Axis-aligned check. */
    if (X <= S && Y <= S) {
        printf("Fits axis-aligned.\n");
        printf("Rotation angle: 0.0 degrees\n");
    }
}

```

```

    printf("Bounding box size: %.6f x %.6f\n", X, Y);
    printf("Place bounding box with min corner at (%.6f, %.6f)\n",
          (S - X) * 0.5, (S - Y) * 0.5);
    return 0;
}

/* 45-degree case. Bounding box is a square of side (X + Y)*sqrt(2)/2. [web:49][web:5
const double SQRT2_OVER_2 = M_SQRT1_2; /* sqrt(2)/2 */
double W = (X + Y) * SQRT2_OVER_2;

if (W <= S) {
    double angle_deg = 45.0;
    double bx = (S - W) * 0.5;
    double by = (S - W) * 0.5;

    printf("Fits at 45 degrees.\n");
    printf("Rotation angle: %.6f degrees\n", angle_deg);
    printf("Bounding box size: %.6f x %.6f\n", W, W);
    printf("Place bounding box with min corner at (%.6f, %.6f)\n",
          bx, by);
    return 0;
}

printf("Does not fit axis-aligned or at 45 degrees.\n");
return 0;
}

```

- `getopt_long` is declared in `<getopt.h>` and is used here with a `struct option` array defining the `--x`, `--y`, `--s`, and `--help` long options, mapped to short options `x`, `y`, `s`, `h`.^[58] ^[59]
- The 45° bounding box formula $(X + Y) \cdot \sqrt{2} / 2$ gives the minimal axis-aligned box size for that orientation, which is then centered in the square to minimize the X and Y extents.^[60] ^[61]

**

Modify that program so that if only one of x or y is given, the maximum value of the other dimension is determined and printed. s must be given.

Yes; with your 0°/45° rule this is straightforward algebra plus some option-parsing logic. If only one of X or Y is given, the other is solved from the relevant inequality and printed.

- Axis-aligned fit: $X \leq S$ and $Y \leq S$.
- 45° fit: $(X + Y) \frac{\sqrt{2}}{2} \leq S \Rightarrow X + Y \leq S\sqrt{2}$.^[80]

Below is an updated program:

```

#define _GNU_SOURCE
#include <stdio.h>
#include <stdlib.h>
#include <getopt.h>

```

```

#include <math.h>

static void usage(const char *prog)
{
    fprintf(stderr,
        "Usage:\n"
        " %s --x <width> --y <height> --s <square_side>\n"
        " %s --x <width> --s <square_side>\n"
        " %s --y <height> --s <square_side>\n"
        "Short forms: -x, -y, -s\n",
        prog, prog, prog);
}

int main(int argc, char *argv[])
{
    double X = 0.0, Y = 0.0, S = 0.0;
    int have_x = 0, have_y = 0, have_s = 0;

    static struct option long_opts[] = {
        { "x",    required_argument, 0, 'x' },
        { "y",    required_argument, 0, 'y' },
        { "s",    required_argument, 0, 's' },
        { "help", no_argument,      0, 'h' },
        { 0, 0, 0, 0 }
    };

    int opt;
    int opt_index = 0;

    while ((opt = getopt_long(argc, argv, "x:y:s:h", long_opts, &opt_index)) != -1) {
        switch (opt) {
            case 'x':
                X = atof(optarg);
                have_x = 1;
                break;
            case 'y':
                Y = atof(optarg);
                have_y = 1;
                break;
            case 's':
                S = atof(optarg);
                have_s = 1;
                break;
            case 'h':
                usage(argv[5_0]);
                return 0;
            default:
                usage(argv[5_0]);
                return 1;
        }
    }

    if (!have_s) {
        fprintf(stderr, "Error: --s <square_side> is required.\n");
        usage(argv[5_0]);
        return 1;
    }
}

```

```

}

if (S <= 0.0) {
    fprintf(stderr, "Error: square side must be positive.\n");
    return 1;
}

/* Case A: only X is given, compute max Y. */
if (have_x && !have_y) {
    if (X <= 0.0) {
        fprintf(stderr, "Error: X must be positive.\n");
        return 1;
    }

    /* Axis-aligned limit: Y <= S. */
    double y_axis = S;

    /* 45-degree limit: X + Y <= S*sqrt(2). [web:17] */
    double y_rot = S * M_SQRT2 - X;

    double y_max;
    int use_axis = 0, use_rot = 0;

    if (y_axis > 0.0)
        use_axis = 1;
    if (y_rot > 0.0)
        use_rot = 1;

    if (!use_axis && !use_rot) {
        printf("No positive Y fits for X = %.6f and S = %.6f.\n", X, S);
        return 0;
    }

    if (use_axis && use_rot)
        y_max = (y_axis < y_rot) ? y_axis : y_rot;
    else if (use_axis)
        y_max = y_axis;
    else
        y_max = y_rot;

    printf("Given X = %.6f, S = %.6f\n", X, S);
    printf("Maximum Y that fits (0° or 45°): %.6f\n", y_max);
    return 0;
}

/* Case B: only Y is given, compute max X. */
if (!have_x && have_y) {
    if (Y <= 0.0) {
        fprintf(stderr, "Error: Y must be positive.\n");
        return 1;
    }

    /* Axis-aligned limit: X <= S. */
    double x_axis = S;

    /* 45-degree limit: X + Y <= S*sqrt(2). [web:17] */

```

```

double x_rot = S * M_SQRT2 - Y;

double x_max;
int use_axis = 0, use_rot = 0;

if (x_axis > 0.0)
    use_axis = 1;
if (x_rot > 0.0)
    use_rot = 1;

if (!use_axis && !use_rot) {
    printf("No positive X fits for Y = %.6f and S = %.6f.\n", Y, S);
    return 0;
}

if (use_axis && use_rot)
    x_max = (x_axis < x_rot) ? x_axis : x_rot;
else if (use_axis)
    x_max = x_axis;
else
    x_max = x_rot;

printf("Given Y = %.6f, S = %.6f\n", Y, S);
printf("Maximum X that fits (0° or 45°): %.6f\n", x_max);
return 0;
}

/* Case C: both X and Y given -> original behavior. */
if (!have_x || !have_y) {
    fprintf(stderr, "Error: must supply either (X and Y) or exactly one of them.\n");
    usage(argv[5_0]);
    return 1;
}

if (X <= 0.0 || Y <= 0.0) {
    fprintf(stderr, "Error: X and Y must be positive.\n");
    return 1;
}

/* Axis-aligned check. */
if (X <= S && Y <= S) {
    printf("Fits axis-aligned.\n");
    printf("Rotation angle: 0.0 degrees\n");
    printf("Bounding box size: %.6f x %.6f\n", X, Y);
    printf("Place bounding box with min corner at (%.6f, %.6f)\n",
           (S - X) * 0.5, (S - Y) * 0.5);
    return 0;
}

/* 45-degree case: bounding box side W = (X + Y)*sqrt(2)/2. [web:17] */
{
    const double SQRT2_OVER_2 = M_SQRT1_2;
    double W = (X + Y) * SQRT2_OVER_2;

    if (W <= S) {
        double angle_deg = 45.0;

```

```

double bx = (S - W) * 0.5;
double by = (S - W) * 0.5;

printf("Fits at 45 degrees.\n");
printf("Rotation angle: %.6f degrees\n", angle_deg);
printf("Bounding box size: %.6f x %.6f\n", W, W);
printf("Place bounding box with min corner at (%.6f, %.6f)\n",
       bx, by);
return 0;
}
}

printf("Does not fit axis-aligned or at 45 degrees.\n");
return 0;
}

```

- The “max other dimension” comes from intersecting the axis-aligned constraint (other side $\leq S$) with the 45° constraint $X + Y \leq S\sqrt{2}$, and taking the smaller positive bound. ^[81] ^[80]
- `getopt_long` handling is unchanged in structure; only the post-parse logic branches on which of `--x/--y` were supplied. ^[82] ^[83]

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